

# Gaussian Process Regression on Nested Spaces

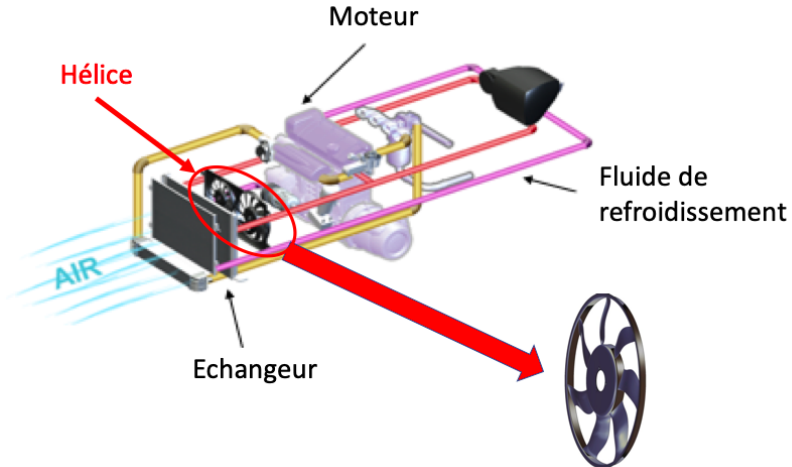
Christophette Blanchet-Scalliet

ICJ-Ecole Centrale de Lyon

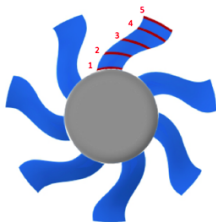
Joint work with T.Gonon (Safran), C. Helbert 5ECL) B. Demory (Valeo)

Clermont-Ferrand, Thursday 21 December 2023

## Motivation- Cooling system

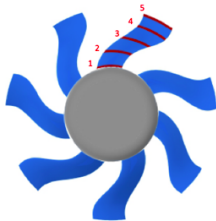


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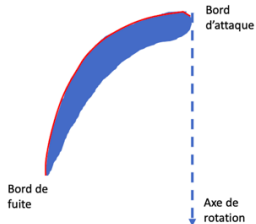


**Sections de pale**

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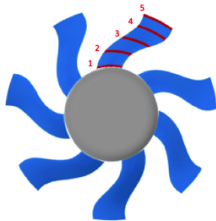


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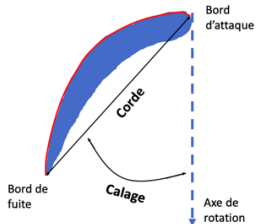


**Calage et longueur de corde**

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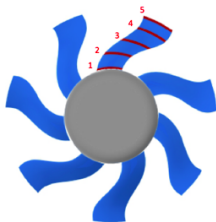


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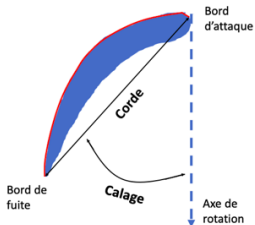


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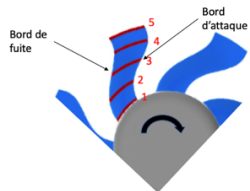
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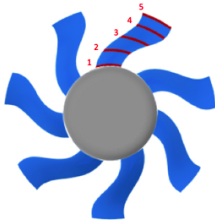


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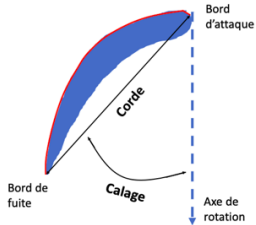


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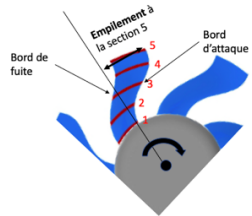
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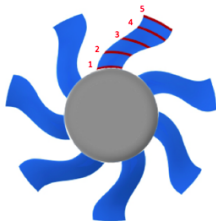


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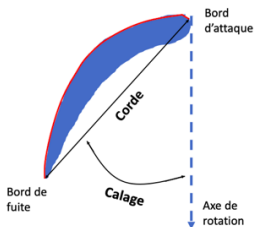


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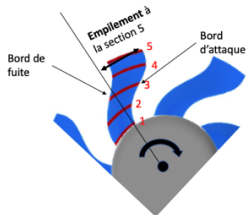
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**Sections de pale**



**Calage et longueur de corde**



**Empilement tangentiel**

### Outputs

- ▶ Pressure difference :  $\Delta P$  (en Pa)



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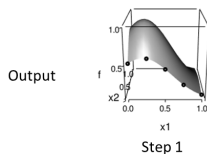
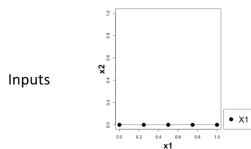
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**Which metamodel adapted to this sequential study ?**

**Aim :** Using all the DoEs.

## Example 2D

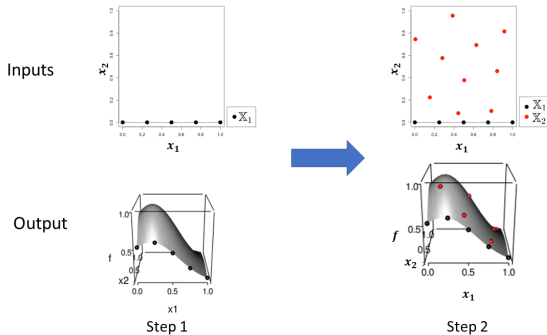
Let  $f$  a function of 2 variables  $f(x_1, x_2) = \exp\left(\frac{(x_1-0.2)^2+(x_2-0.4)^2}{0.3}\right)$ .





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What kind of metamodel ?

# Outline

## seqGPR model

- Kriking

- New Model

- Correction process

## Parameters estimation

## Applications

- Analytic example in dimension 4

- Industrial Test Cases

## Conclusion

# Table des matières

## seqGPR model

Kriking

New Model

Correction process

## Parameters estimation

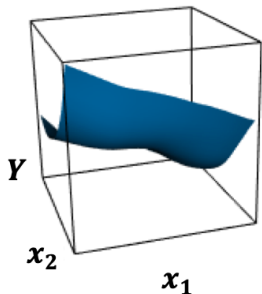
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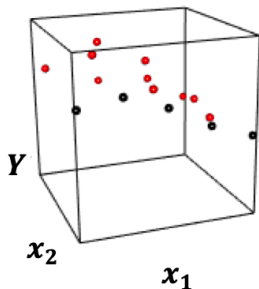
# Classical Gaussian process regression [Santner et al., 2003]



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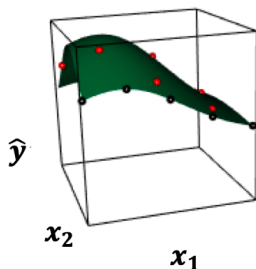


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Prediction :

$$\hat{y}(x_1, x_2) = m + k((x_1, x_2), \mathbb{X})k(\mathbb{X}, \mathbb{X})^{-1}(\mathbf{y} - m)$$

## Parameters inference

$Y \sim \mathcal{PG}(m, k_{(\sigma^2, \theta)})$  with

$$k((x_1, x_2), (x'_1, x'_2)) = \sigma^2 \prod_{i=1}^2 \left( 1 + \frac{\sqrt{5} |x_i - x'_i|}{\theta_i} + \frac{5(x_i - x'_i)^2}{3\theta_i^2} \right) \exp \left( -\frac{\sqrt{5} |x_i - x'_i|}{\theta_i} \right)$$

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$$\mathcal{L}(Y(\mathbb{X}) = \mathbf{y}; \eta) = \frac{1}{(2\pi)^{\frac{n_{\mathbb{X}}}{2}} |k(\mathbb{X}, \mathbb{X})|^{\frac{1}{2}}} \exp \left( -\frac{(\mathbf{y} - m)^T k(\mathbb{X}, \mathbb{X})^{-1} (\mathbf{y} - m)}{2} \right)$$

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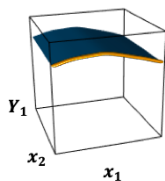
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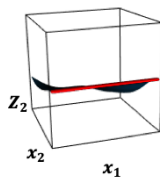
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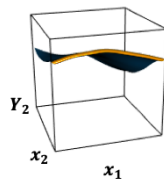
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 $f(x_1, 0)$  réalisation de  $Y_1(x_1)$

+



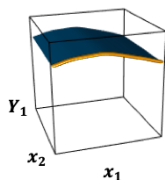
**Processus correctif :**  
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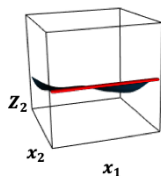
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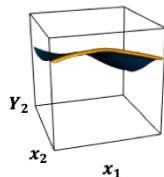
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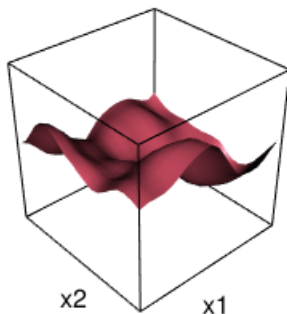


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**Aim : Build  $Z_2$  such that  $Z_2(x_1, 0) = 0$  ?**

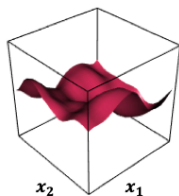
## Idea

Build  $Z_2(x_1, x_2)$  such that  $Z_2(x_1, 0) = 0$  form a latent process  
 $\tilde{Z}_2 \sim \mathcal{PG}(0, \kappa)$  with a kernel  $\kappa$  fixed.

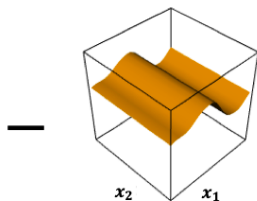


## Red (reduced) process)

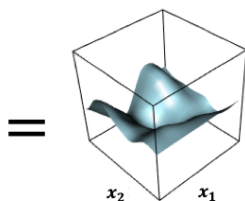
Red process is defined by  $Z_2^{Red}(x_1, x_2) = \tilde{Z}_2(x_1, x_2) - \tilde{Z}_2(x_1, 0)$ .



Processus Latent :  
 $\tilde{Z}_2(x_1, x_2)$



Valeur sur la droite :  
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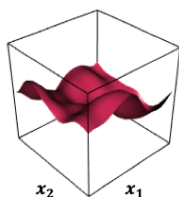


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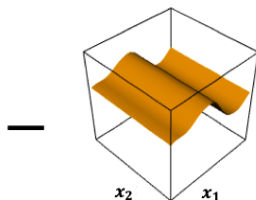
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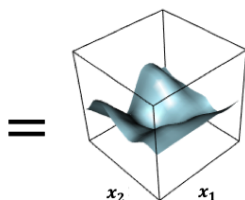
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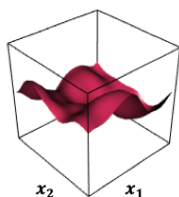
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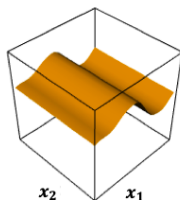
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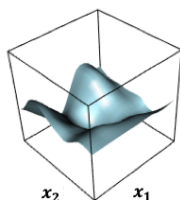
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Processus Red :

$$Z_2^{Red}(x_1, x_2)$$

$$Z_2^{Red} \sim \mathcal{PG}(0, k_2) \text{ with } k_2((x_1, x_2), (x'_1, x'_2)) = \kappa((x_1, x_2), (x'_1, x'_2)) + \kappa((x_1, 0), (x'_1, 0)) - \kappa((x_1, 0), (x'_1, x'_2)) - \kappa((x_1, x_2), (x'_1, 0)).$$

## P (preconditioned) process

The process P is defined using conditional expectation introduced by [Gauthier and Bay, 2012]

$$Z_2^P(x_1, x_2) = \tilde{Z}_2(x_1, x_2) - \mathbb{E} \left[ \tilde{Z}_2(x_1, x_2) \mid \tilde{Z}(\mathcal{D}) \right]$$

with

$$\mathcal{D} = \{(t_1, 0), t_1 \in [0, 1]\}$$

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### Proposition

If the process  $\tilde{Z}_2 \sim \mathcal{PG}(0, \kappa)$  has a tensor product kernel

$$\kappa((x_1, x_2), (x'_1, x'_2)) = \kappa_1(x_1, x'_1)\kappa_2(x_2, x'_2)$$

Then the conditional expectation is equal to :

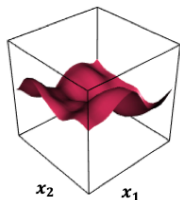
$$\mathbb{E} \left[ \tilde{Z}_2(x_1, x_2) \mid \tilde{Z}(\mathcal{D}) \right] = \kappa_2(x_2, 0)\tilde{Z}_2(x_1, 0)$$

## P (preconditioned) process

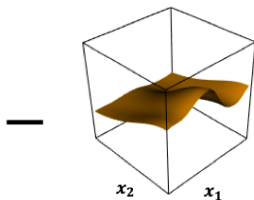
If  $\tilde{Z}_2 \sim \mathcal{PG}(0, \kappa)$  with  $\kappa((x_1, x_2), (x'_1, x'_2)) = \kappa_1(x_1, x'_1)\kappa_2(x_2, x'_2)$ ,

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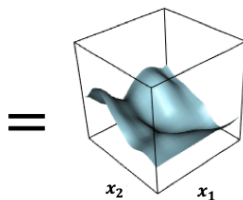
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Processus Latent :  
 $\tilde{Z}_2(x_1, x_2)$



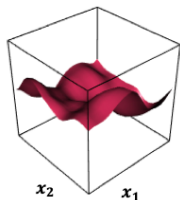
Projection sur la droite:  
 $\kappa_2(x_2, 0)\tilde{Z}_2(x_1, 0)$



Processus P :  
 $Z_2^P(x_1, x_2)$

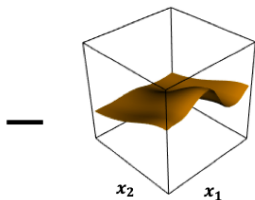
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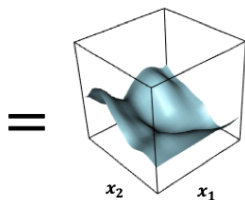
Processus Latent :

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Projection sur la droite:

$$\kappa_2(x_2, 0)\tilde{Z}_2(x_1, 0)$$



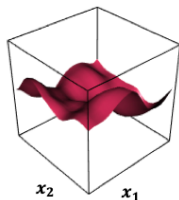
Processus P :

$$Z_2^P(x_1, x_2)$$

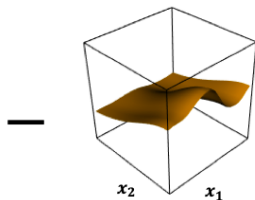
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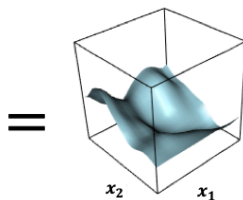
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Processus Latent :  
 $\tilde{Z}_2(x_1, x_2)$



Projection sur la droite:  
 $\kappa_2(x_2, 0)\tilde{Z}_2(x_1, 0)$



Processus P :  
 $Z_2^P(x_1, x_2)$

$$Z_2^P \sim \mathcal{PG}(0, k_2) \text{ with} \\ k_2((x_1, x_2), (x'_1, x'_2)) = \kappa_1(x_1, x'_1) [\kappa_2(x_2, x'_2) - \kappa_2(x_2, 0)\kappa_2(x'_2, 0)].$$



## Interpretation of the correction process

Latent process  $\tilde{Z}_2 \sim \mathcal{GP}(0, \kappa)$

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⇒ global disruption

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Latent process  $\tilde{Z}_2 \sim \mathcal{GP}(0, \kappa)$

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$$Z_2^{Red}(x_1, x_2) = \tilde{Z}_2(x_1, x_2) - \tilde{Z}_2(x_1, 0)$$

⇒ global disruption

- ▶ P process :

$$Z_2^P(x_1, x_2) = \tilde{Z}_2(x_1, x_2) - \kappa_2(x_2, 0)\tilde{Z}_2(x_1, 0)$$

⇒ local disruption

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# Estimation Problem

## Estimation Problem

- ▶ Model :  $Y_2(x_1, x_2) = Y_1(x_1) + Z_2(x_1, x_2)$  with
  - ▶  $Y_1 \sim \mathcal{PG}(m, k_1)$ ,  $k_1$  stationary
  - ▶  $Z_2 \sim \mathcal{PG}(0, k_2)$ , Red or P  $\Rightarrow Z_2(x_1, 0) = 0$
  - ▶  $Z_2 \perp Y_1$

## Estimation Problem

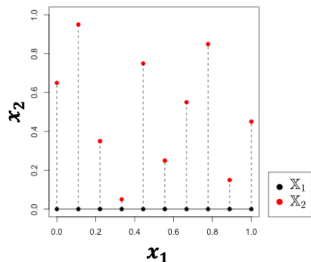
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- ▶ We need to estimate  $\eta = (\eta_1, \eta_2)$  with  $\eta_1$  parameters of  $Y_1$  and  $\eta_2$  parameters of  $Z_2$ . We have  $(\mathbb{X}_1, \mathbf{y}_1)$  and  $(\mathbb{X}_2, \mathbf{y}_2)$ .

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- ▶ Maximum of (Log-)likelihood  $\mathcal{LL}(Y_1(\mathbb{X}_1) = \mathbf{y}_1, Y_2(\mathbb{X}_2) = \mathbf{y}_2; \eta)$



## Nested Designs



Nested designs

### Decoupled Log-likelihood:

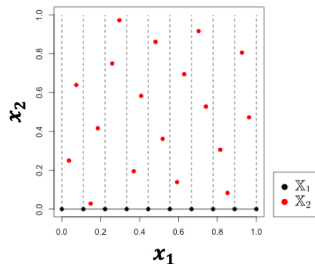
- ▶  $\eta_1$  : parameters of  $Y_1$

$$\max_{\eta_1} \mathcal{LL}(Y_1(\mathbb{X}_1) = \mathbf{y}_1; \eta_1)$$

- ▶  $\eta_2$  : parameters of  $Z_2$

$$\max_{\eta_2} \mathcal{LL}(Z_2(\mathbb{X}_2) = \mathbf{z}_2; \eta_2)$$

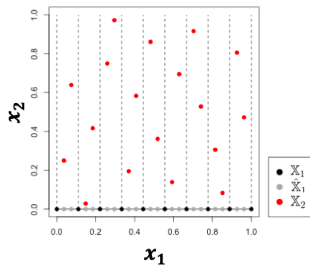
## Non-Nested designs



Problem :  $\mathcal{L}\mathcal{L}(Y_1(\mathbb{X}_1) = y_1, Y_2(\mathbb{X}_2) = y_2; \eta)$  can't be decoupled.

**Non-nested designs**

## Non-Nested designs

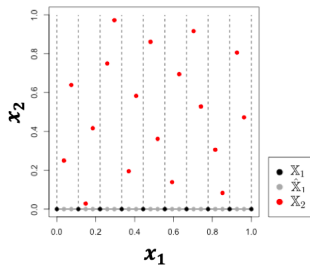


Nested designs

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Nested designs

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$\Rightarrow \mathcal{L}\mathcal{L}(Y_1(\tilde{\mathbb{X}}_1) = \tilde{\mathbf{y}}_1, Y_2(\mathbb{X}_2) = \mathbf{y}_2; \eta)$   
 can be now decoupled in  $\mathcal{L}\mathcal{L}(Y_1(\tilde{\mathbb{X}}_1) = \tilde{\mathbf{y}}_1; \eta_1) \mathcal{L}\mathcal{L}(Z_2(\mathbb{X}_2) = \mathbf{z}_2; \eta_2)$

## Expectation-Maximization (EM) [Hastie et al., 2009]

EM algorithm is defined by sequences

$$(\hat{\mathcal{L}}^{(i)}(Y_1(\tilde{\mathbb{X}}_1) = \tilde{\mathbf{y}}_1; \eta_1))_i, (\hat{\mathcal{L}}^{(i)}(Z_2(\mathbb{X}_2) = \mathbf{z}_2; \eta_2))_i, \text{ et } (\eta^{(i)})_i.$$

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► Maximization :

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## Function and data

Let the function

$$f(x_1, x_2, x_3, x_4) = f_1(x_1, x_2) + f_2(x_1, x_2, x_3, x_4)$$

with

$$\begin{cases} f_1(x_1, x_2) &= \left[ 4 - 2.1(4x_1 - 2)^2 + \frac{(4x_1 - 2)^4}{3} \right] (4x_1 - 2)^2 \\ &+ (4x_1 - 2)(2x_2 - 1) + [-4 + 4(2x_2 - 1)^2] (2x_2 - 1)^2 \\ f_2(x_1, x_2, x_3, x_4) &= 4 \exp(-\|x - 0.3\|^2) \end{cases}$$

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- ▶ At step 1, let the restriction  $f(x_1, x_2, \frac{x_1+x_2}{2}, 0.2x_1 + 0.7)$ . Computer code evaluations at DoE  $(\mathbb{X}_1, y_1)$  of size 20.

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- ▶ At step 2, new simulations of  $f$  at points DoE  $(\mathbb{X}_2, y_2)$ , a design in dimension 4 and of size 40.

## Benchmark models

- ▶ **K\_tot** : Kriging ( $Y \sim \mathcal{PG}(m, k)$ ) trained on  $(\mathbb{X}_1, y_1)$  and  $(\mathbb{X}_2, y_2)$ .

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- ▶ **seqGPR** : Kriging ( $(Y_2 \sim \mathcal{PG}(m, k_1 + k_2))$ ) trained on  $(\mathbb{X}_1, y_1)$  and  $(\mathbb{X}_2, y_2)$ .

$$\begin{cases} Y_2(x_1, x_2, x_3, x_4) & = Y_1(x_1, x_2) + Z_2(x_1, x_2, x_3, x_4) \\ Z_2(x_1, x_2, \frac{x_1+x_2}{2}, 0.2x_1 + 0.7) & = 0, \end{cases}$$

- ▶  $Y_1 \sim \mathcal{PG}(m, k_1)$
- ▶  $Z_2 \sim \mathcal{PG}(0, k_2)$  a process **Red** or **P** built from  $\tilde{Z}_2$ .
- ▶  $\tilde{Z}_2 \sim \mathcal{PG}(0, \kappa)$  independent of  $Y_1$  with robust parametrization  $\kappa$  :  $(\alpha, \alpha, \theta_3, \theta_4)$ .

$k, k_1$ , et  $\kappa$  are Matern  $\frac{5}{2}$  tensor-product.

## Results

RMSE on a Sobol sequence of size 10000. Median and interquartile range of RMSE on 100 samples  $(\mathbb{X}_1, y_1)$  of size 20,  $(\mathbb{X}_2, y_2)$  of size 40. **Red** is better.

	K_2	K_tot	P	Red
Médian	0.44	0.17	0.12	<b>0.07</b>
Interquartile range	0.05	0.09	0.05	<b>0.02</b>



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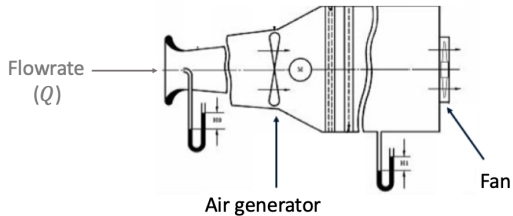
Others studies show that the size of the of the training sample has non influence.

## Fan System in a cooling system

### Input

## Fan System in a cooling system

**Input**  
Flowrate



## Fan System in a cooling system

### Input

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

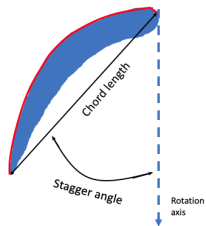
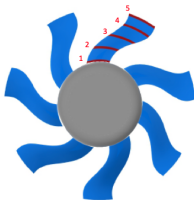
LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5



# Fan System in a cooling system

## Input

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

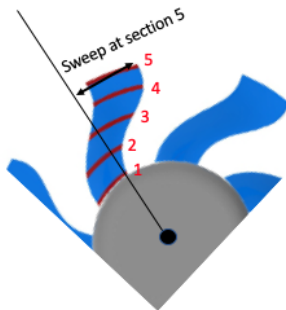
LChord\_5

Sweep\_2

Sweep\_3

Sweep\_4

Sweep\_5



## Fan System in a cooling system

### Input

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2

Sweep\_3

Sweep\_4

Sweep\_5

**Output :**  $\Delta P$

# Data

# Data

## Step 1

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2=1

Sweep\_3=1

Sweep\_4=0.82

Sweep\_5=0.517645



# Data

## Step 1

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2=1

Sweep\_3=1

Sweep\_4=0.82

Sweep\_5=0.517645

## Step 2

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2

Sweep\_3

Sweep\_4

Sweep\_5

# Data

## Step 1

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2=1

Sweep\_3=1

Sweep\_4=0.82

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## Step 2

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2

Sweep\_3

Sweep\_4

Sweep\_5

- ▶ 30 models
- ▶  $\mathbb{X}_1$  : 50 points in  $[0, 1]^{11}$
- ▶  $\mathbb{X}_2$  : 50 points in  $[0, 1]^{15}$

## Data

## Step 1

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2=1

Sweep\_3=1

Sweep\_4=0.82

Sweep\_5=0.517645

## Step 2

Flowrate

Stagger\_1

Stagger\_2

Stagger\_3

Stagger\_4

Stagger\_5

LChord\_1

LChord\_2

LChord\_3

LChord\_4

LChord\_5

Sweep\_2

Sweep\_3

Sweep\_4

Sweep\_5

- ▶ 30 models
- ▶  $\mathbb{X}_1$  : 50 points in  $[0, 1]^{11}$
- ▶  $\mathbb{X}_2$  : 50 points in  $[0, 1]^{15}$

	Median	Range
<b>K_tot</b>	44.6	5.9
<b>P</b>	<b>41.2</b>	4.7
<b>Red</b>	42.1	<b>4.6</b>

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- ▶ EM Algorithm to estimate the model EM pour estimer les paramètres
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Thank you for your attention

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